

School of Industrial Engineering and Telecommunications

SUBJECT TEACHING GUIDE

G739 - Automatic Control Systems

Degree in Mechanical Engineering

Academic year 2023-2024

1. IDENTIFYING DATA							
Degree	Degree in Mechanical Engineering			Type and Year	Compulsory. Year 2		
Faculty	School of Industrial Engineering and Telecommunications						
Discipline	Subject Area: Electronics and Automation Module in Common with the Industrial Branch						
Course unit title and code	G739 - Automatic Control Systems						
Number of ECTS credits allocated	6	Term Semeste		ər based (1)			
Web	https://moodle.unican.es/course/view.php?id=3544						
Language of instruction	Spanish	English Friendly	No	Mode of o	delivery	Face-to-face	

Department	DPTO. TECNOLOGIA ELECTRONICA E INGENIERIA DE SISTEMAS Y AUTOMATICA
Name of lecturer	LUCIANO ALONSO RENTERIA
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Other lecturers	ELIAS REVESTIDO HERRERO

3.1 LEARNING OUTCOMES

- Starting from the principles and mathematical techniques used in Control Engineering, to get to know the methods of analysis and design in the temporal domain and in the frequency domain. Knowledge of some software tools for modeling and simulation of systems.

4. OBJECTIVES

Achieve the learning results described in section 3.1 of the subject.



6. COURSE ORGANIZATION		
CONTENTS		
1	INTRODUCTORY CONCEPTS Introduction to Methods and Techniques for Industrial Control. Control systems. Industrial Automation: Definition, Types and Classification, Technology and examples.	
2	MODELING OF SYSTEMS AND TRANSFER FUNCTION. The Laplace transform. Mathematical model of physical systems. Transfer function. Block diagrams Linearization of non-linear systems.	
3	TEMPORARY ANALYSIS OF CONTINUOUS SYSTEMS. Stability analysis Response analysis in steady state. Analysis of response in transitory regim	
4	BASIC CONTROL ACTIONS. Control in open loop and closed loop. Control all-nothing. PID control. Experimental tuning of PID regulators.	
5	THE METHOD OF THE ROOTS LOCUS. Introduction. Properties of the roots locus. Rules for the construction of the roots locus. Inverse roots locus. Generalized roots locus. Contour of the roots. Design of regulators through the roots locus.	
6	FREQUENCY ANALYSIS OF CONTROL SYSTEMS. Introduction. Sinusoidal transfer function. Representation diagrams of the frequency response. Plotting of the asymptotic Bode diagram. Stability analysis in the frequency domain. Operating specifications in the frequency domain. Design of regulators in the frequency domain.	



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7. ASSESSMENT METHODS AND CRITERIA					
Description	Туре	Final Eval.	Reassessn	%	
First control theory	Written exam	No	Yes	30,00	
First practical control	Laboratory evaluation	No	Yes	20,00	
theory final exam	Written exam	Yes	Yes	30,00	
Final practical exam	Laboratory evaluation	Yes	Yes	20,00	
TOTAL 100,00					
Observations					
Given the uncertain current health situation, in the event that the competent health and educational authorities so indicate, not allowing the development of any evaluation activity in person in the classroom, a distance evaluation modality will be adopted using telematic means.					
Observations for part-time students					
Students enrolled part-time may choose to be evaluated using the method described above for other students, or through a single final exam, which will consist of a written part of theory (60% of the weight) and a part of laboratory practices.					

8. BIBLIOGRAPHY AND TEACHING MATERIALS	
BASIC	
INSTRUMENTATION AND CONTROL SYSTEMS. W. Bolton	
INGENIERÍA DE CONTROL MODERNA. K. Ogata	
SISTEMAS DE CONTROL AUTOMÁTICO. B.C. Kuo	
SISTEMAS CONTINUOS DE CONTROL. J.M. Pérez Oria	
PROBLEMAS DE INGENIERÍA DE SISTEMAS CONTINUOS. CONCEPTO	S BASICOS. J.R. Llata García, E. González
Sarabia, D. Fernández Pérez, J. Arce Hernando, J.M. Pérez Oria	(Disponible en OCW:
http://ocw.unican.es/ensenanzas-tecnicas/automatica)	